

FIG. 1

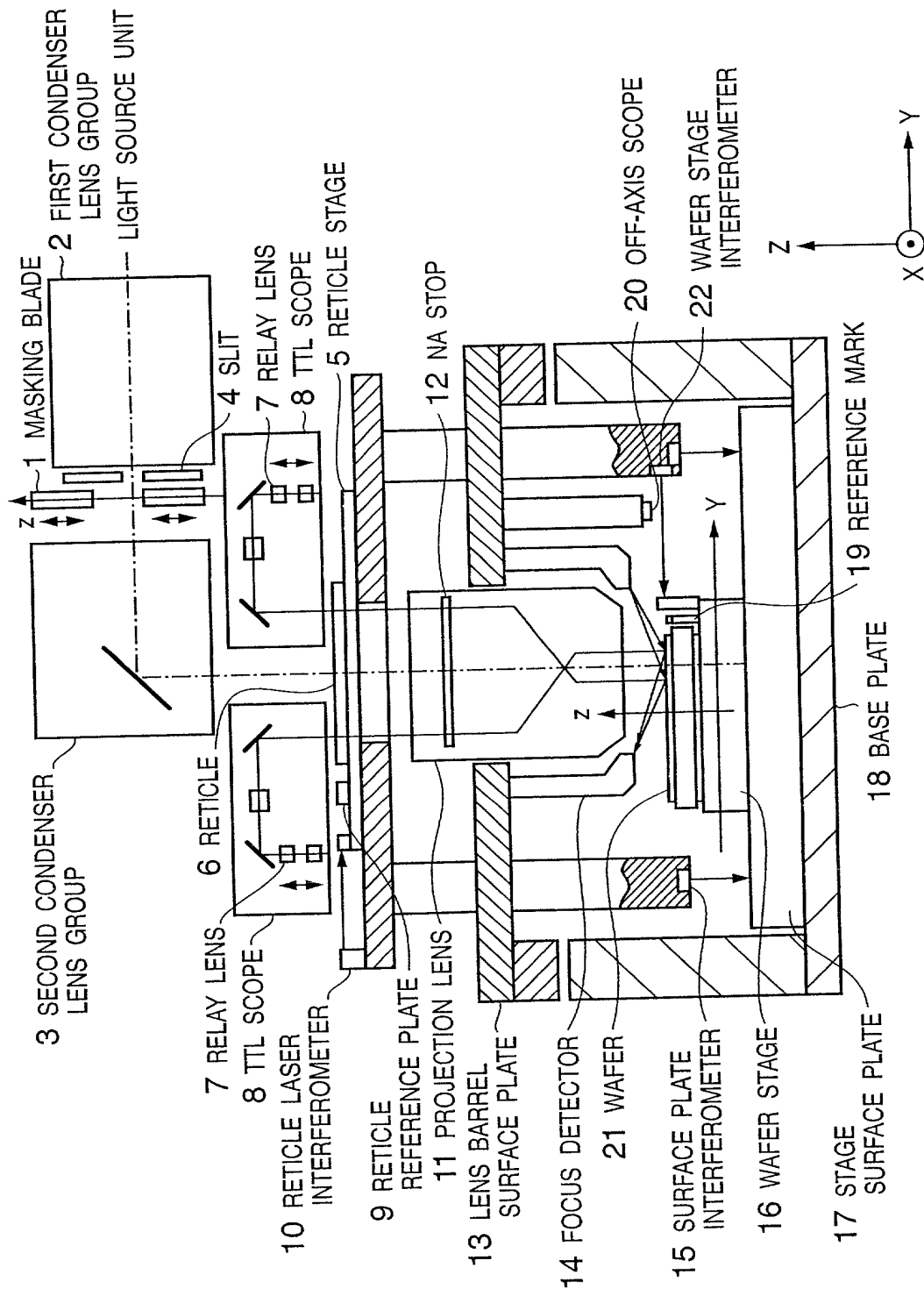
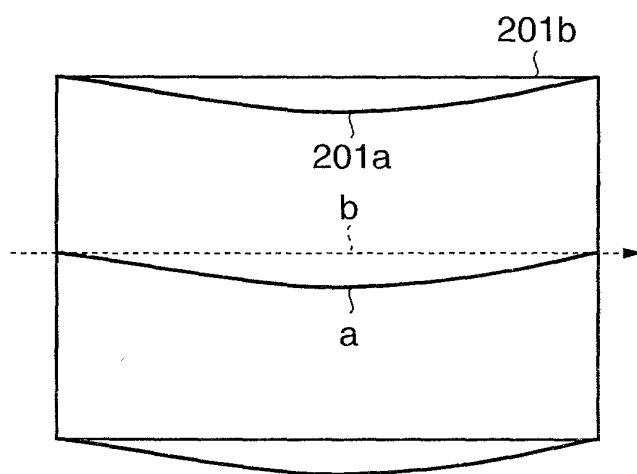
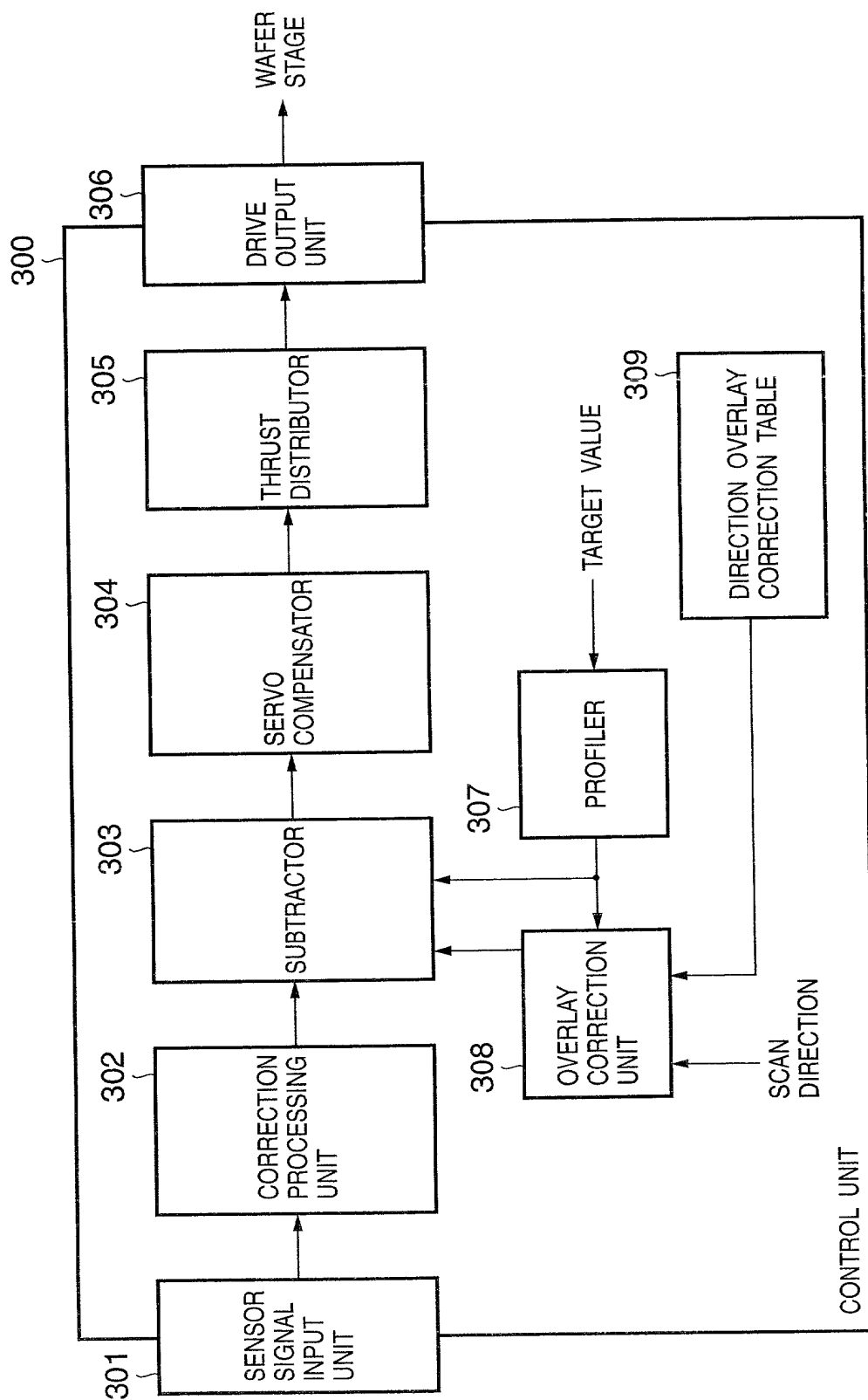


FIG. 2



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The diagram illustrates a coordinate transformation system for a projection optical system, organized into two main horizontal paths (410a and 410b) and a final correction stage (417).

- Path 410a (Left):**
 - Inputs **401** (X1), **402** (X2), and **403** (Y) are fed into block **410a** (ENVIRONMENTAL CORRECTION).
 - Block **410a** outputs to block **411** (MIRROR SURFACE REFORMATION).
 - Block **411** outputs to block **416a** (MAGNIFICATION CORRECTION).
 - Block **416a** outputs coordinates X'' , θ'' , and Y'' to block **417**.
 - Block **416a** also receives input X' from block **415** (1/Lq).
 - Block **415** receives input θ' from block **413** (a summing junction).
 - Block **413** receives inputs from block **411** and block **414b**.
- Path 410b (Right):**
 - Inputs **404** (E1), **405** (E2), and **406** (E3) are fed into block **412a** (COORDINATE TRANSFORMATION).
 - Block **412a** outputs to block **414a** (a summing junction).
 - Block **414a** outputs coordinate Z'' to block **417**.
 - Block **414a** also receives input Z' from block **414b**.
 - Block **414b** receives inputs from block **412a** and block **414c**.
 - Block **414c** receives inputs from block **412b** and block **414b**.
 - Block **412b** (COORDINATE TRANSFORMATION) receives inputs **407** (L1), **408** (L2), and **409** (L3) from block **410b** (ENVIRONMENTAL CORRECTION).
 - Block **410b** receives inputs from block **412a** and block **414c**.
 - Block **410b** outputs to block **416b** (MAGNIFICATION CORRECTION).
 - Block **416b** outputs coordinates $\omega X''$ and $\omega Y''$ to block **417**.
 - Block **416b** also receives inputs $\omega X'$ and $\omega Y'$ from block **414b**.
- Final Stage (417):**
 - Block **417** (INTER-AXIAL INTERFERENCE CORRECTION (ABBE)) receives the final corrected coordinates X'' , θ'' , Y'' , Z'' , $\omega X''$, and $\omega Y''$.
 - Block **417** outputs the final system coordinates X , θ , Y , Z , ωX , and ωY .

FIG. 5

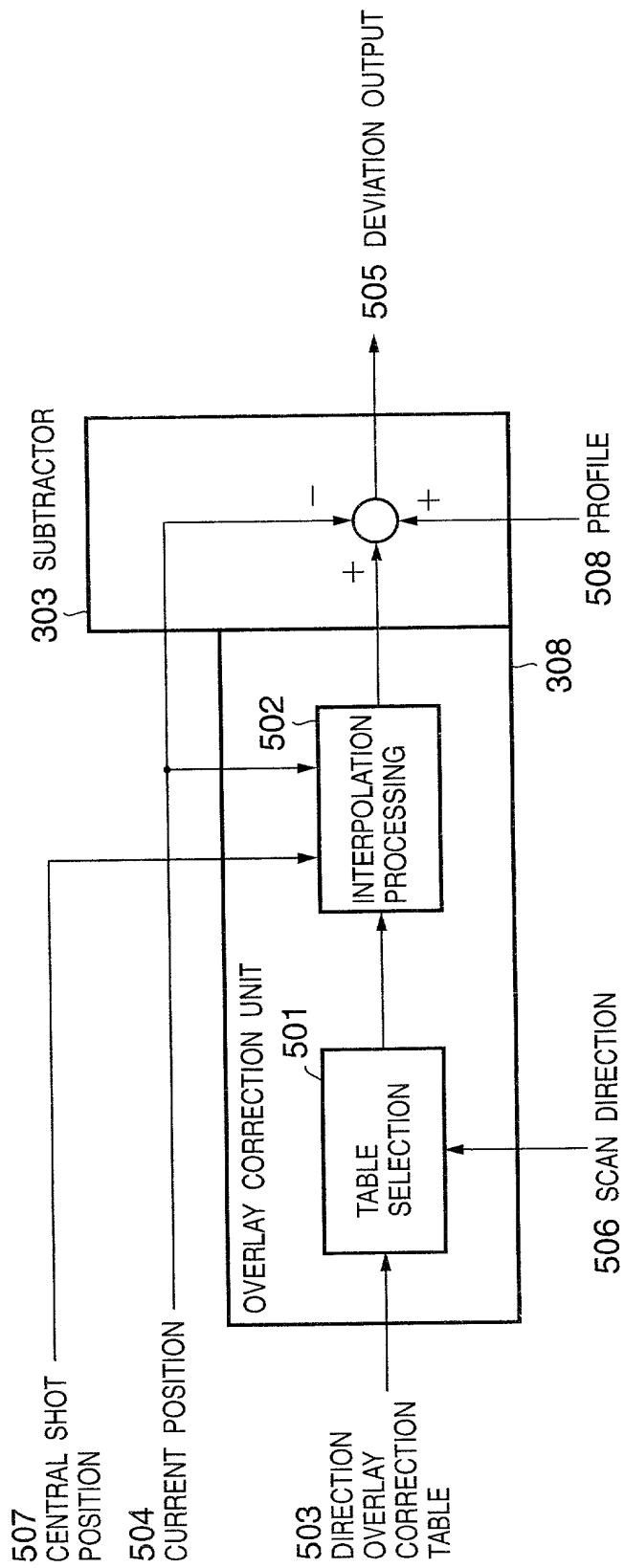


FIG. 6

ORIGIN	-16.000		[mm]		
INTERVAL	4.000		[mm]		
CORRECTION DATA			[nm/ppb]		
(FORWARD)					
X	Y	Z	Qx	Qy	Qz
5	1	10	0	-10	20
4	1	8	10	-10	10
2	0	10	20	20	10
1	-1	12	20	40	10
-1	-4	13	20	30	0
-4	-2	10	40	40	-10
-3	-4	7	10	50	-30
-6	-5	4	0	80	-30
-12	-9	0	-20	60	-40
(REVERSE)					
X	Y	Z	Qx	Qy	Qz
4	0	9	10	-10	20
2	0	6	0	0	10
0	-1	11	10	10	10
0	-1	11	20	30	20
-3	-4	10	40	10	0
-5	-3	9	20	40	-10
-5	-4	6	20	60	-30
-7	-5	4	10	100	-30
-14	-9	-1	0	80	-30

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FIG. 7

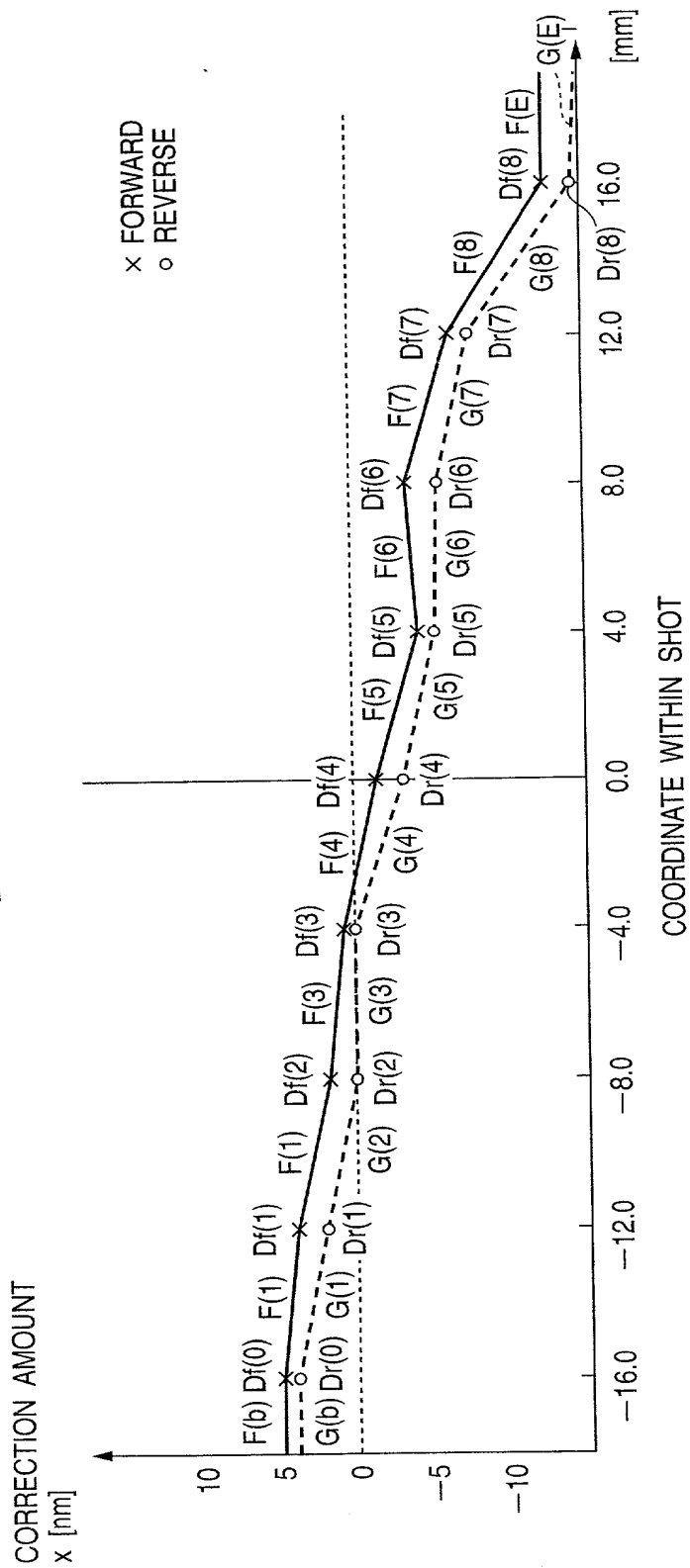


FIG. 8

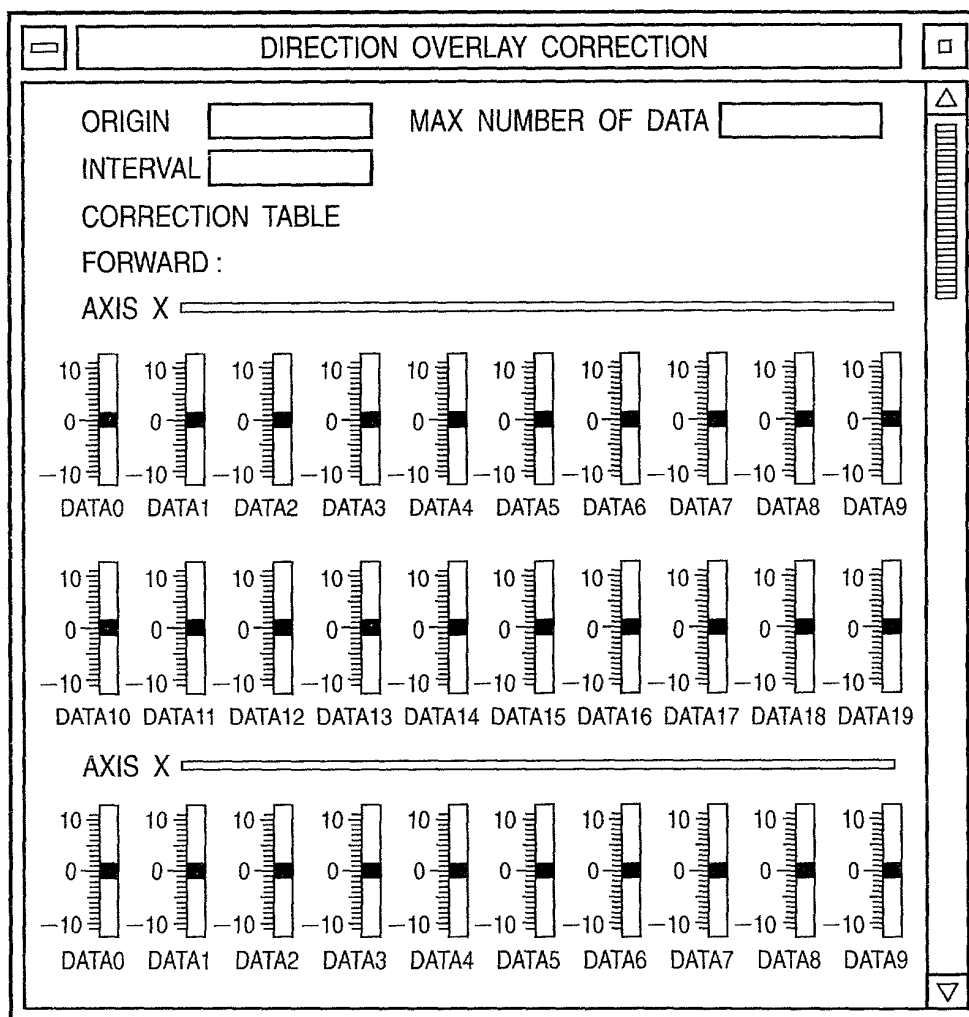


FIG. 9

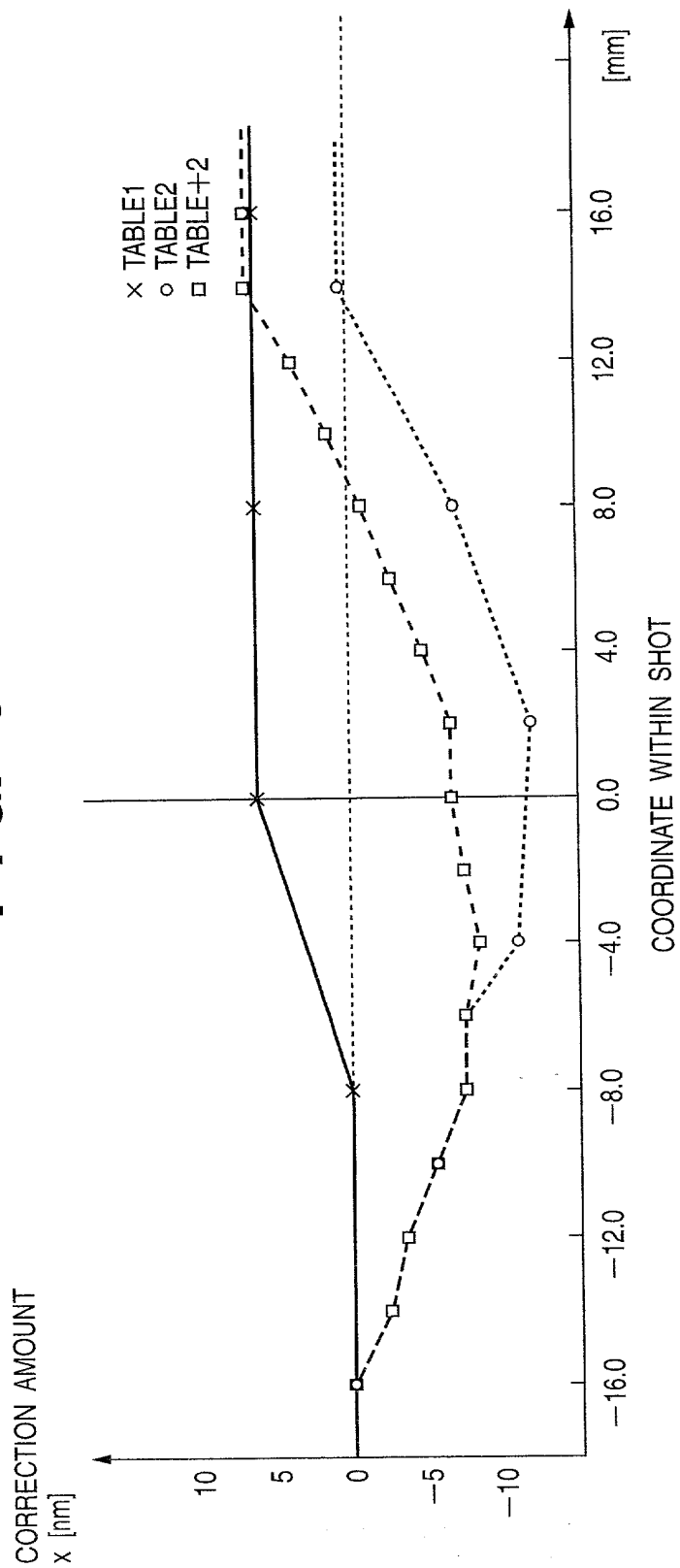


FIG. 10

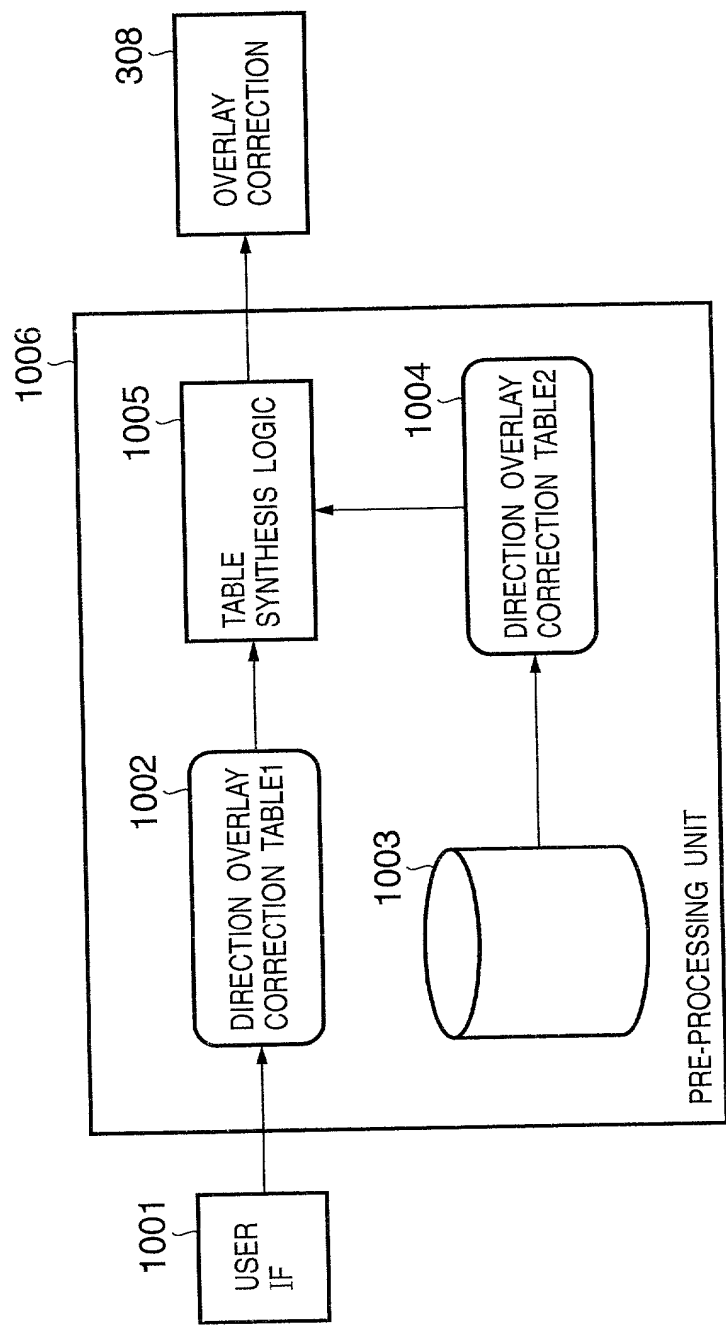


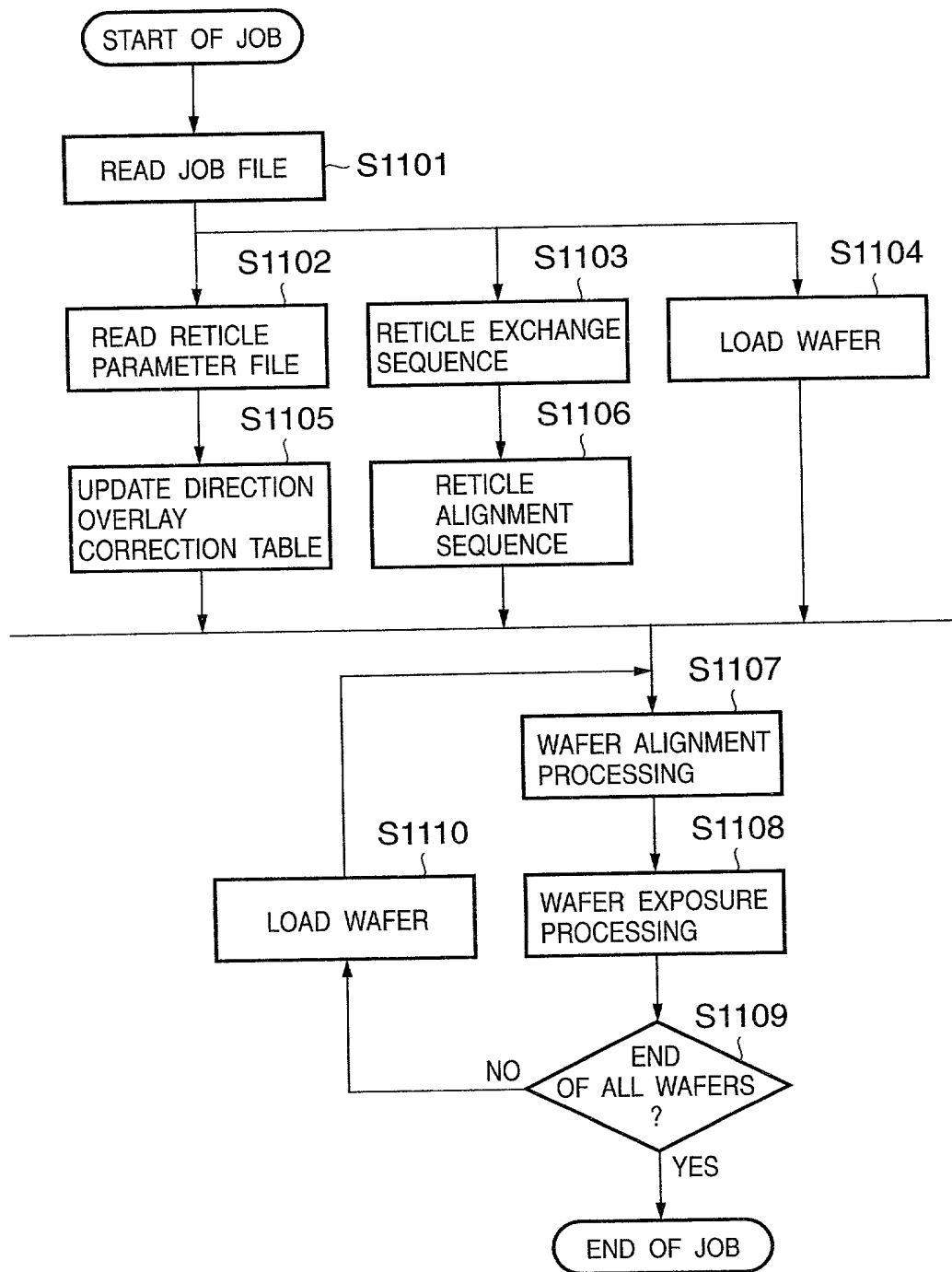
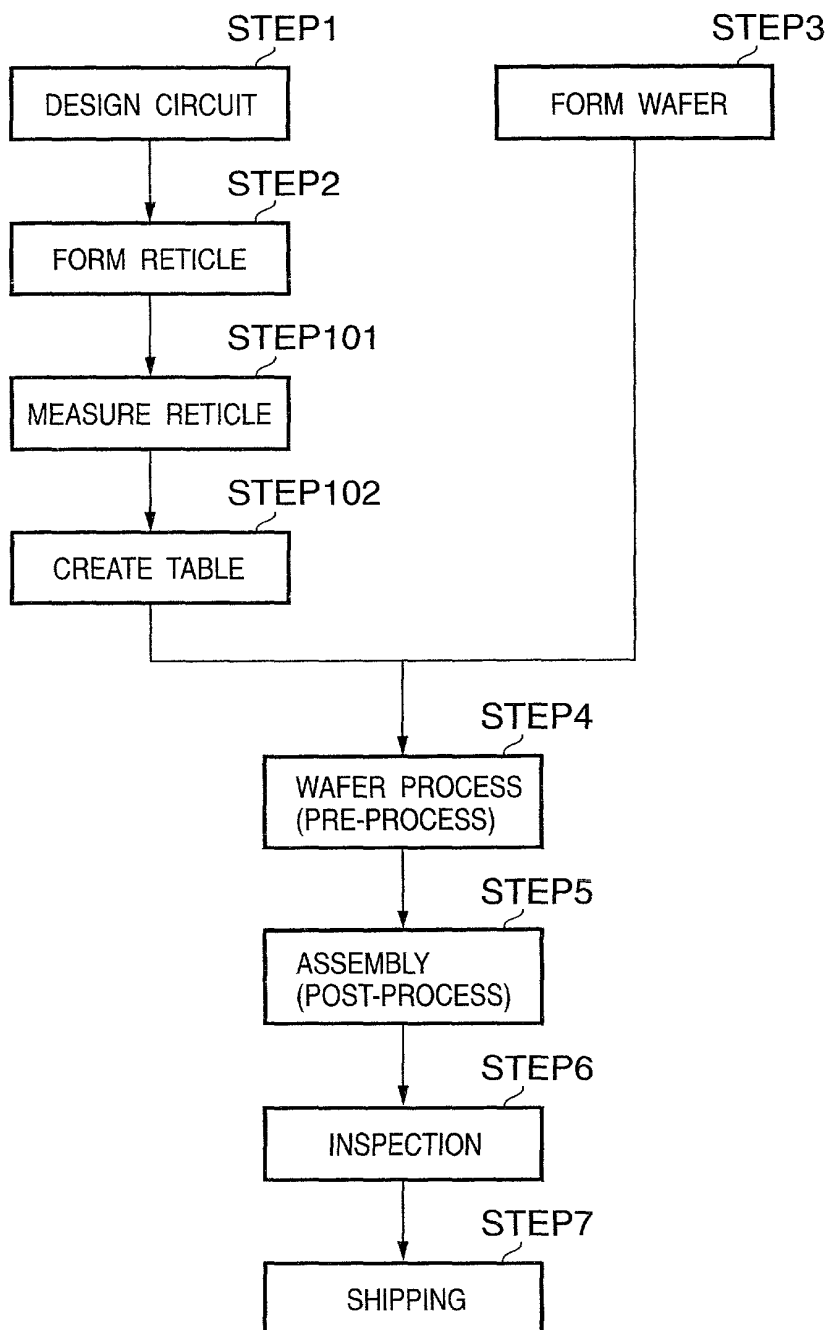
FIG. 11

FIG. 12

SEMICONDUCTOR DEVICE MANUFACTURING FLOW

FIG. 13

